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EVOLUTION AND DISTRIBUTION OF CURRENT HELICITY IN FULL-SUN SIMULATIONS

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ABSTRACT

Current helicity quantifies the location of twisted and sheared non-potential structures in a magnetic field. We simulate the evolution of magnetic fields in the solar atmosphere in response to flux emergence and shearing by photospheric motions. In our global-scale simulation over many solar rotations the latitudinal distribution of current helicity develops a clear statistical pattern, matching the observed hemispheric sign at active latitudes. In agreement with observations there is significant scatter and intermixing of both signs of helicity, where we find local values of current helicity density that are much higher than those predicted by linear force-free extrapolations. Forthcoming full-disk vector magnetograms from Solar Dynamics Observatory will provide an ideal opportunity to test our theoretical results on the evolution and distribution of current helicity, both globally and in single active regions.

Subject headings: Sun: activity — Sun: magnetic fields

1. INTRODUCTION

The twist of the solar magnetic field plays an important role in transient phenomena such as solar flares and coronal mass ejections, and in the dynamo processes that cause the 11-year solar activity cycle. The magnetic twist can be measured in various ways. Magnetic helicity is an integral that quantifies topological complexity of field lines, such as linking, twist, or kinking (Berger 1998, 1999). For a closed magnetic system it is defined by $H_m = \int \mathbf{A} \cdot \mathbf{B} d^3x$, and alternative definitions have been developed for open systems (Berger & Field 1984; Finn & Antonsen 1985).

In this letter we consider current helicity, which we define as

$$\alpha = \frac{\mathbf{j} \cdot \mathbf{B}}{B^2}, \quad (1)$$

where \mathbf{B} is the magnetic field and $\mathbf{j} = \nabla \times \mathbf{B}$ is the current density. The quantity α has the advantage that it describes the *local* distribution of twist and shear in the magnetic field, and that it is more readily determined from limited observational data than H_m which requires global information. For a force-free field ($\mathbf{j} \times \mathbf{B} = 0$) we have $\mathbf{j} = \alpha \mathbf{B}$ and α , which may be a function of space, is a fundamental parameter that describes the torsion of the field lines around one another. Note that we shall not consider the *integral* current helicity $H_c = \int \mathbf{j} \cdot \mathbf{B} d^3x$ because unlike H_m it is not a near-conserved quantity in MHD (Démoulin 2007), and it does not even in general take the same sign as H_m (except for linear force-free fields where α is constant in space and α , H_c , and H_m all have the same sign, Hagyard & Pevtsov 1999).

There are two main techniques for estimating α from observed vector magnetograms, which so far only cover a small region of the solar surface such as a single active region:

1. Compute $j_z = \partial B_y / \partial x - \partial B_x / \partial y$ and hence $\alpha_z = j_z / B_z$, which should give α exactly for a force-free field (Abramenko et al. 1996; Bao & Zhang 1998).

2. Compute a linear force-free extrapolation from B_z and choose the overall value, α_{best} , which best reproduces the observed B_x , B_y distribution over the region (Pevtsov et al. 1995; Longcope et al. 1998; Zhang 2006).

The studies by Hagino & Sakurai (2004) and Burnette et al. (2004) show that both techniques are generally consistent. The key result of these observations is a robust hemispheric rule whereby the average α value is negative in the northern hemisphere and positive in the southern hemisphere, although there is significant scatter including a mixture of signs of α within single active regions. This hemispheric pattern in α has also been found by Pevtsov et al. (2001) who reconstructed the radial and toroidal components of the global magnetic field under simplifying assumptions.

A trans-equatorial sign change in helicity is supported by numerous proxy observations such as H α images of active region structure (Hale 1927), *in situ* heliospheric measurements (Smith & Bieber 1993), differential rotation (Berger & Ruzmaikin 2000), and filament/prominence magnetic fields (Rust 1967; Martin et al. 1994). Using newly-developed simulations of the global coronal evolution, we have recently been able to reproduce the filament hemispheric pattern including exceptions (with 96% agreement), in a comparison with 109 observed filaments (Yeates et al. 2007, 2008). In this letter we describe the distribution of current helicity in a 30-month simulation, which we hope to compare with new magnetic observations from the SDO (NASA Solar Dynamics Observatory) mission.

2. CORONAL MODEL

Our simulations of the 3D coronal field evolution (Yeates et al. 2008) use the coupled flux transport and magnetofrictional model of van Ballegoijen et al. (2000), in a domain extending from 0° to 360° in longitude, -80° to 80° in latitude, and R_\odot to $2.5R_\odot$ in radius. The coronal magnetic field $\mathbf{B} = \nabla \times \mathbf{A}$ evolves *via* the non-ideal induction equation

$$\frac{\partial \mathbf{A}}{\partial t} = \mathbf{v} \times \mathbf{B} - \eta_c \mathbf{j}, \quad (2)$$

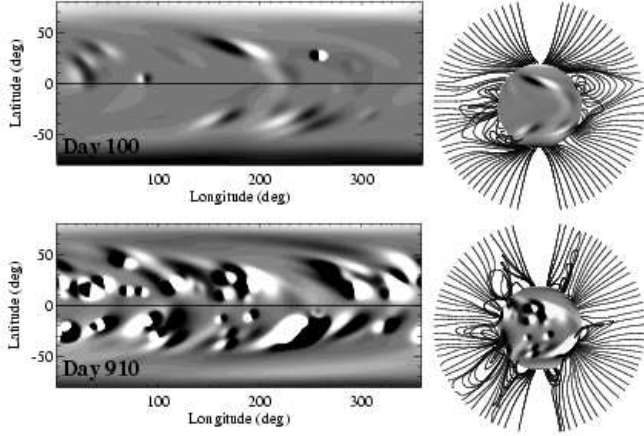


FIG. 1.— Simulated magnetic field on days 100 (*top*) and 910 (*bottom*). Left column shows radial magnetic field on solar surface (white for positive, black for negative), and right column shows selected field lines of the 3D coronal magnetic field.

in response to flux emergence and advection by large-scale motions on the photospheric boundary. Rather than solve the full MHD system we approximate the momentum equation by the magnetofrictional method (Yang et al. 1986), setting

$$\mathbf{v} = \frac{1}{\nu} \frac{\mathbf{j} \times \mathbf{B}}{B^2} + v_{\text{out}}(r) \hat{\mathbf{r}}. \quad (3)$$

This artificial velocity ensures evolution through a sequence of near force-free states. The second term is a radial outflow imposed only near to the upper boundary, where it simulates the effect of the solar wind in opening up field lines in the radial direction (Mackay & van Ballegoijen 2006). The diffusivity η_c consists of a uniform background term and an enhancement in regions of strong current density \mathbf{j} (see Mackay & van Ballegoijen 2006).

The photospheric boundary conditions are described in Yeates et al. (2007); the surface flux transport model includes newly emerging magnetic bipoles based on active regions observed in synoptic normal-component magnetograms from NSO, Kitt Peak. The emerging bipoles take a simple mathematical form, with properties chosen to match the location, size, tilt, and magnetic flux of the observed regions. They are inserted in 3D with a non-zero twist (magnetic helicity), chosen to match the observed sign of helicity in each hemisphere. The simulation illustrated in this letter models 30 months of continuous evolution during the rising phase of Cycle 23 (from 1997 April 9 to 1999 October 10, rotations CR1921 to CR1954). From an initial potential field extrapolation, the photospheric and coronal fields were evolved forward continuously for 914 days with 396 new bipoles inserted during this time. Two example snapshots of the simulated magnetic field are shown in Figure 1.

3. SOURCES OF HELICITY IN SINGLE ACTIVE REGIONS

To illustrate the sources of current helicity in our simulation within an individual active region, Figure 2 zooms in to a bipole in the northern hemisphere which emerged on day 136 (as measured from the start of the simulation).

There are three main sources of coronal currents and helicity in our model:

1. The new bipoles emerge twisted. This twist is initially concentrated low down in the centre of the bipole, as seen from the field lines in Figure 2(a) which are

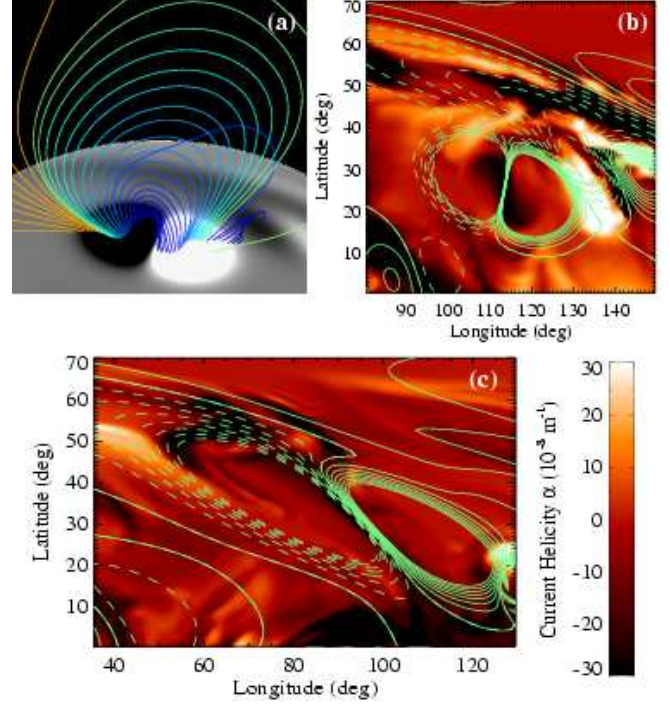


FIG. 2.— Structure of a single bipolar region, showing (a) magnetic field structure, (b) distribution of current helicity α on day 140, and (c) distribution of α on day 190. In (a) grey shading shows radial magnetic field strength on the solar surface (black negative, white positive), and coloured lines show selected coronal field lines. In (b) and (c) contours of α at height 14Mm are shown in colour scale, and green contours show strength of radial surface magnetic field (solid for positive, dashed for negative).

skewed as they cross the bipole's central polarity inversion line (PIL). The sigmoidal concentration of negative α at the centre of the bipole is clearly seen on day 140 in Figure 2(b).

2. When the bipoles emerge they displace older fields and produce currents at the interface between old and new flux systems (see Yeates et al. 2008). In Figure 2(b) this is visible at the NW edge of the new bipole where it adjoins a pre-existing bipole, and a layer of positive α has developed. Note that this is opposite in sign to that from the twist of the new region, as seen in Figure 2(a). This corresponds to field lines that are oppositely skewed at this edge of the new bipole, as compared to those across the central PIL. This is just one example of how both signs of α may naturally be produced within a single active region, as found in observations.
3. Over time, surface motions shear the coronal field generating further currents. This is visible in Figure 2(c), which shows the distribution of α for the same region on day 190, after 50 days evolution. There is a significant build-up of negative α , particularly at the North and South ends of the bipole where helicity was initially low. This build-up is caused by differential rotation and convergence (due to supergranular diffusion).

In addition to these sources of current helicity, it may also be locally reduced by diffusive cancellation and reconnection. Also, helicity is periodically removed through the top boundary of the domain when excessive build-up of twist leads to localised temporary losses of equilibrium, and the ejection of twisted flux ropes (Mackay & van Ballegoijen 2006).

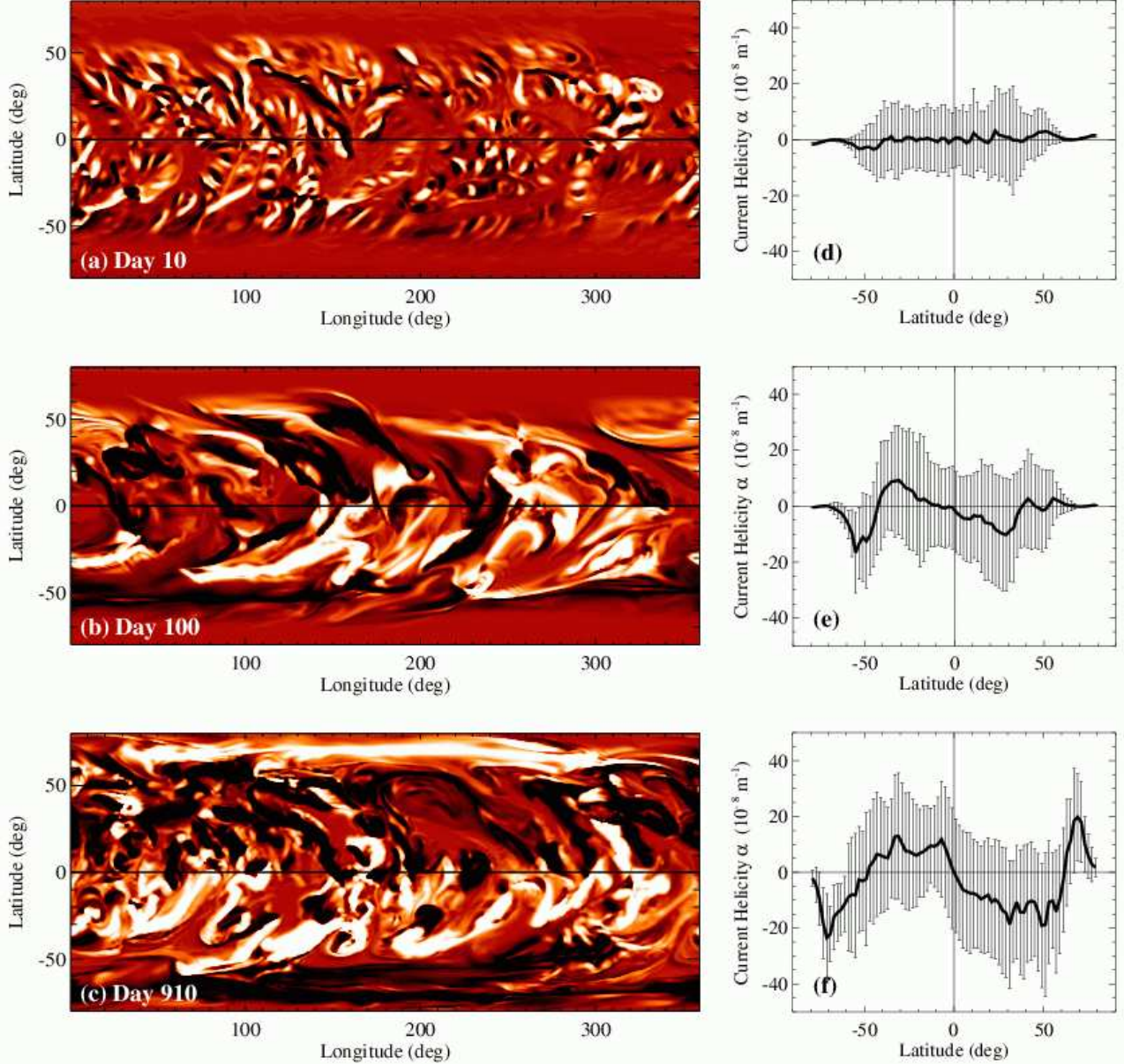


FIG. 3.— Global distribution of α at height 14Mm on days 10, 100, and 910. Left column shows contours of α (white for positive and black for negative, saturation level $\pm 20 \times 10^{-8} \text{ m}^{-1}$). Right column shows latitudinal profile, averaged over longitude in 2° latitude bins. Error bars show one standard deviation.

4. GLOBAL DISTRIBUTION OF CURRENT HELICITY

The global distribution of current helicity, α , is shown in Figure 3 at days 10, 100, and 910 of the simulation. From the initial potential field on day 0 (with $\alpha = 0$ everywhere), a pattern of intermixed positive and negative α has developed by day 10, simply due to photospheric shearing—this is before the first active region emergence. After about 100 days, a clear latitudinal trend in α emerges, although there is still significant local variation in both strength and sign. This pattern persists for the rest of the simulation, and up to medium heights in the 3D corona (nearer the top of the computational box high values of α become localized to closed field regions, with $\alpha \approx 0$ where the field is open).

In Figures 3(a), (e), and (f), it can be seen how the mean α at low latitudes (0° to about 50°) develops into the observed hemispheric trend, although with considerable scatter as observed on the real Sun. However, at high latitudes

the sign of α is reversed. These polar reversals correspond to the East-West PILs at the polar crown boundaries, and move steadily poleward through the simulation as the polar crowns reduce in size towards polar field reversal (we are approaching solar maximum). This opposite sign of α is caused by differential rotation of the predominantly North-South field lines at this latitude, and is a well-documented problem for theoretical models (van Ballegoijen & Martens 1990; Rust & Kumar 1994). At lower latitudes, as was illustrated by Figure 2(c), differential rotation of North-South PILs produces the observed hemispheric sign of helicity (Zirker et al. 1997).

Figure 3 shows mean values of α at active latitudes of the order 10^{-7} m^{-1} . The actual maximum and minimum values recorded on day 910 of the simulation were $2.24 \times 10^{-6} \text{ m}^{-1}$ and $-1.84 \times 10^{-6} \text{ m}^{-1}$. A key result of this study is that these values are much higher than those estimated from linear

force-free extrapolations. Such solutions suffer a constraint on the maximum α in order to obtain a decay with height (Aulanier & Démoulin 1998), requiring that $\alpha < 2\pi/L_x$ (the “first resonant value”), where L_x is the horizontal length of the periodic box. The linear force-free model of an observed filament by Aulanier et al. (2000) has $\alpha = 2.3 \times 10^{-8} \text{ m}^{-1}$, and for the solutions of Mackay et al. (1999) this first resonant value was at $\alpha = 4.24 \times 10^{-8} \text{ m}^{-1}$. By contrast, studies using nonlinear force-free extrapolations from vector magnetograms using the Grad-Rubin type method (Amari et al. 1997) find locally higher values of α (e.g., Bleybel et al. 2002). They are also more realistic because they allow variable α within a single region, as in our simulations. For a particular active region, Régnier et al. (2002) found maximum values of the order 10^{-6} m^{-1} , consistent with the results of our simulations.

5. DISCUSSION

In this letter we have shown how our 3D simulations of the global coronal magnetic field evolution are able to model the development and transport of current helicity, α , over many solar rotations. We find a clear latitudinal pattern of α that persists throughout the simulation, although locally within single bipoles there is significant scatter and intermixing of both signs of α , in agreement with observations. Local values may be much higher than those predicted by linear force-free extrapolations.

With existing measurements of α limited to vector magnetograms of individual active regions, robust observations of the latitudinal distribution of α await full-disk vector magnetograms. These will shortly be available from the NASA Solar Dynamics Observatory (SDO) satellite. In particular the HMI (Helioseismic and Magnetic Imager) instrument will provide synoptic full-disk vector magnetograms at 1” resolution and approximately 90 s cadence. This will offer an exciting opportunity to test and refine our theoretical model for the coronal magnetic field. In particular, consistent measurements over a

large portion of the solar cycle will allow us to consider how the helicity distribution varies over both space and time.

Whether there is a systematic variation in the latitudinal trend of helicity over the solar cycle remains an unresolved issue (Sokoloff et al. 2006; Pevtsov et al. 2008), and has implications for the sub-surface origin of helicity (Choudhuri et al. 2004). Indeed Kleeorin et al. (2003) showed that observations of α in active regions provide important constraints on theories of the solar dynamo itself (see also Sokoloff 2007). Ejection of helical fields from the corona, as included in our simulations, is also thought to play an important role in sustaining the solar cycle (Blackman & Brandenburg 2003).

A particular feature of our results is the sign reversal of current helicity at the high-latitude polar crowns. This would appear to be in conflict with observations of magnetic fields in polar crown filaments, which show no such reversal in their chirality pattern (Rust 1967; Leroy et al. 1983; Martin et al. 1994). We hope to address this outstanding issue in longer simulations covering a greater portion of the solar cycle. It is not at present clear whether longer-term poleward transport of the correct sign of helicity will be enough to counteract the effect of differential rotation on the North-South oriented field lines at these latitudes. Observations of vector magnetic fields in the polar regions, such as those being made by *Hinode* (Lites et al. 2008) and soon the SDO mission, should help to constrain our models.

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